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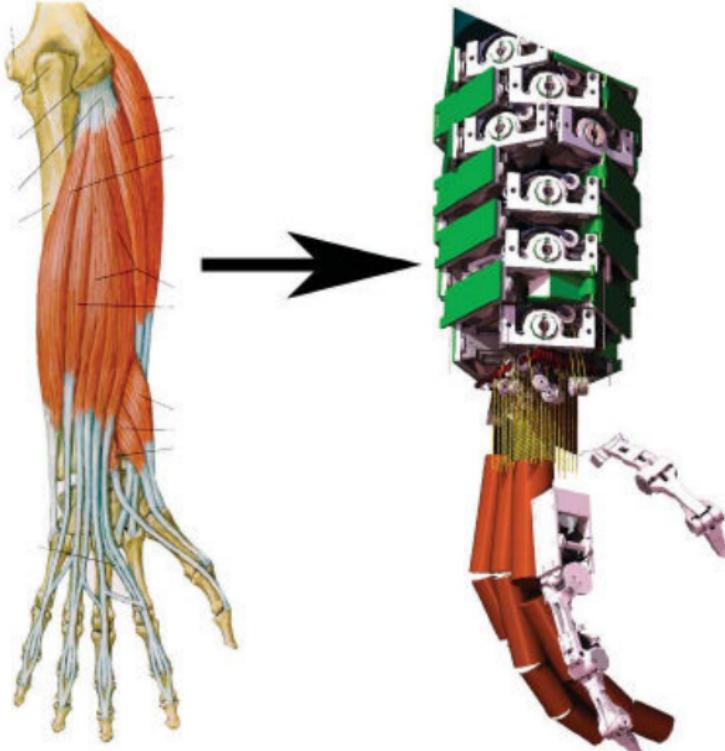


Tailoring Machine Learning to Textile-embedded Sensors

Matthew Howard

July 23, 2018





Robot Learning Lab

- Human behaviour modelling, extraction, understanding.
- Imitation learning, programming by demonstration.
- Optimal feedback control, reinforcement learning.
- Humanoid robotics, variable impedance actuation.
- Natural interfaces for capturing human behaviour.

weights
nonfunctional
algorithm
start
generic
drawing around
since
positions
linear
matrix
set
show
end
cost
gplvm
two
dpl
stiffness
commands
hand
risk
wayable
findaction
due
generic
must
command
provide
ref.
dof
case
strained three
local
hand
wrist
axis
forward
take
line
angle
space
position
model
policies
note
tracking
method
finally
demonstration
based
learning
robot
different

Robots? . . . Textiles?

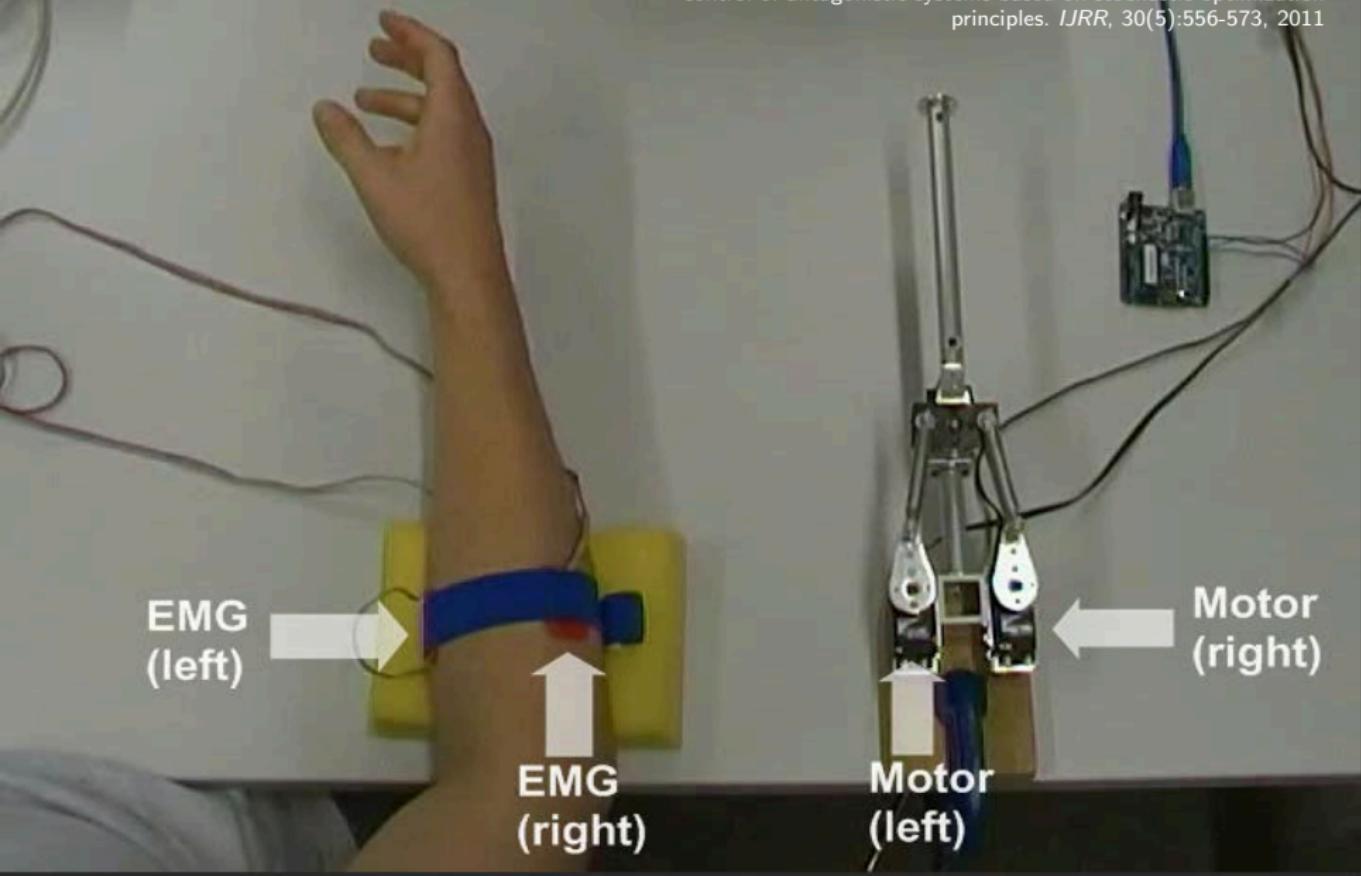


Programming by Demonstration



MH, D. Braun, & S. Vijayakumar. Transferring human impedance behavior to heterogeneous variable impedance actuators. *IEEE T-Ro*, 29(4):847-862, 2013

D. Mitrovic, S. Klanke, & S. Vijayakumar. Learning impedance control of antagonistic systems based on stochastic optimization principles. *IJRR*, 30(5):556-573, 2011



Myographic Prosthesis Control



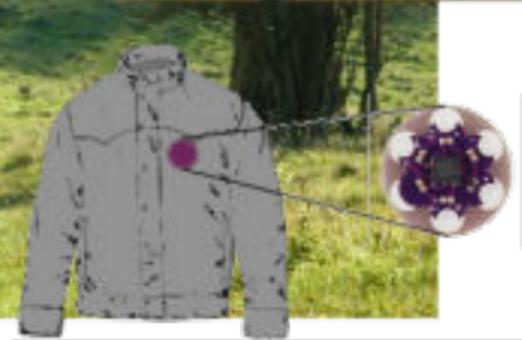
Measuring natural motion



R. B. R. Manero, et al. Wearable embroidered muscle activity sensing device for the human upper leg. *EMBC 2016*, D. Roetenberg, H. Luinge, & P. Slycke. Xsens mvn: full 6dof human motion tracking using miniature inertial sensors. Tech. rep., Xsens Motion Technologies, 2009, L. Buechley & M. Eisenberg. The lilypad arduino: Toward wearable engineering for everyone. *IEEE Pervasive*, 7:12-15, 2008

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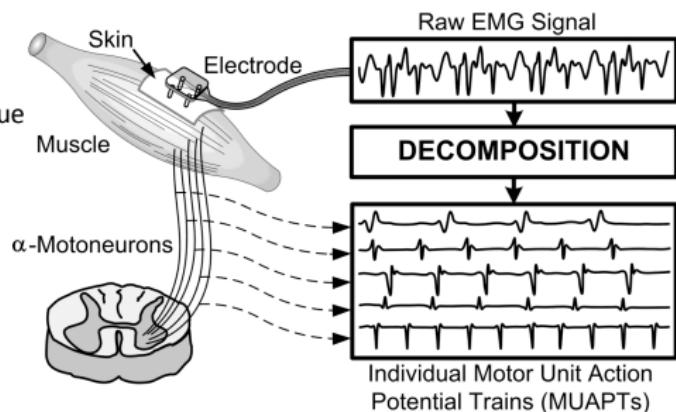
Measuring natural motion



Measuring natural motion

Surface Electromyography (sEMG)

- Non-invasive but **obtrusive**
- Allows monitoring of muscle activity, effort and fatigue
- Applications in
 - Gait monitoring
 - Effort assessment
 - Robotic prosthetics
 - Human-robot interaction
 - Ergonomics and comfort assessments

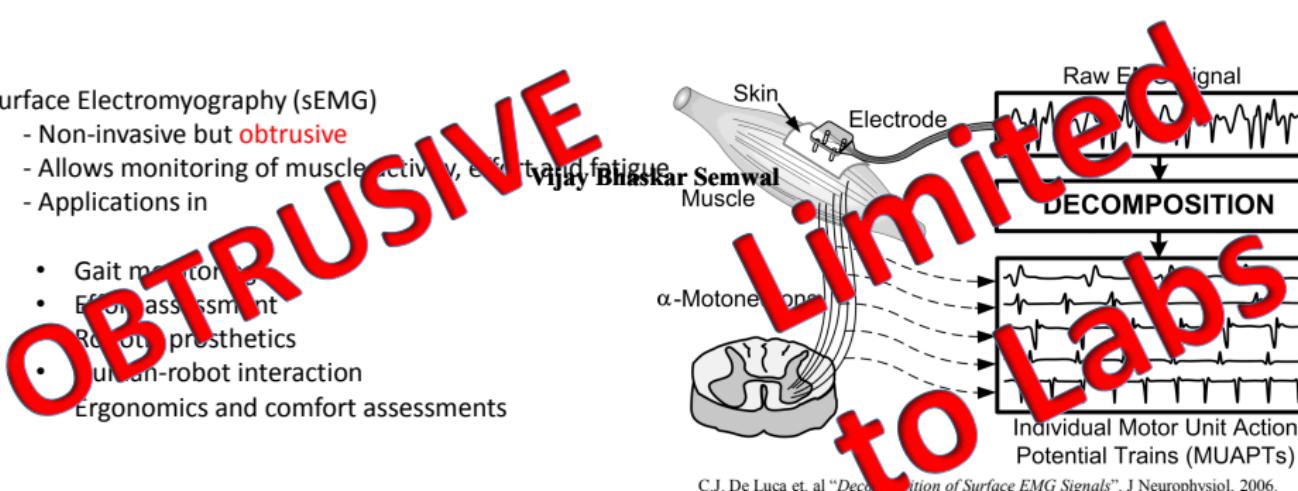


C.J. De Luca et. al "Decomposition of Surface EMG Signals", J Neurophysiol, 2006.

Measuring natural motion

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Muscles, Getting a Stitch!

Karina Thompson
Matthew Howard

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